

IFT 4031/7031,
Machine Learning for Signal Processing
**Week 10: Graphs in Signal Processing
and Machine Learning**

Cem Subakan



UNIVERSITÉ
LAVAL



- Do not forget to fill in the project sign-up sheet!
It's first come first serve.
 - ▶ N'oubliez pas le sign-up sheet pour les projets. C'est premier arrivé premier servi.
- There will be a last homework to be done in groups.
 - ▶ Il y aura un dernier devoir à faire en groupes!

Today's Lecture

- Graphs!
- Using Graphs instead of vectors / matrices
 - ▶ On va utiliser des graphs au lieu de vecteurs / matrices
- Graph Signal Processing Basics
 - ▶ Les bases du traitement du signal avec des graphs
- Graph Machine Learning
 - ▶ De l'apprentissage automatique avec des graphs

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Graph Basics

Example Graphs

Graph Signal Processing

The Graph Laplacian

Graph Fourier Transform

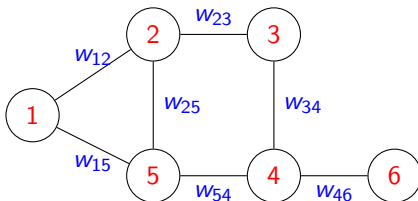
Graph Signal Processing in Action

Graph Convolution

Graph Neural Networks

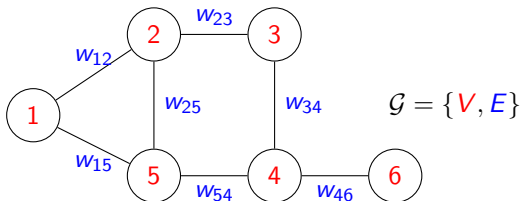
Graph

- A graph is a set of vertices (nodes) and edges.



Graph

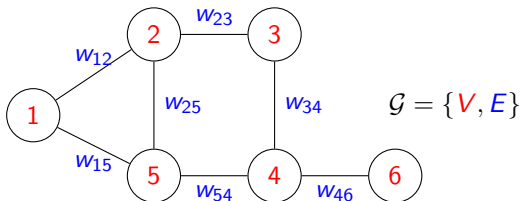
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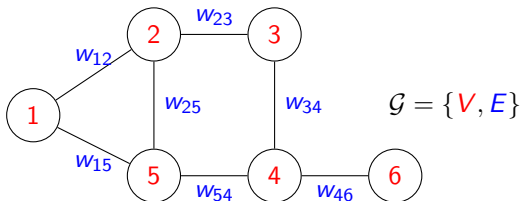
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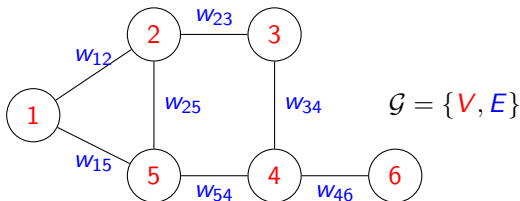
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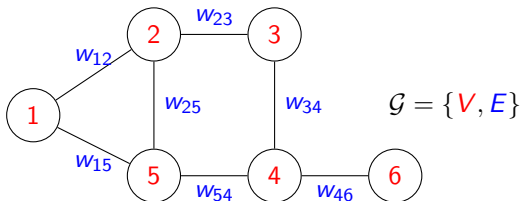
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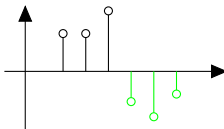
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- Graphs might be directed or undirected. / Undirected: $1 \rightarrow 2 = 2 \rightarrow 1$
 - ▶ Les graph peut etre directionnel ou non.
- Graphs model **pairwise** relationships.
 - ▶ Les graphs modèle des relations **par paires**.

Representing a Signal as a Graph

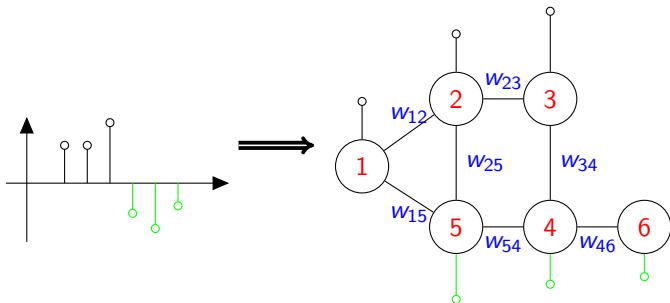
- Associate each sample of the signal to a node. / On va associer chaque échantillon du signal avec un vertex.
 - ▶ Example: $x = [0.5, 0.5, 0.8, -0.4, -0.6, -0.3]$.



Representing a Signal as a Graph

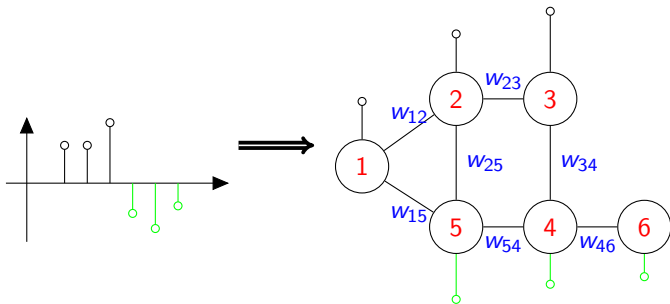
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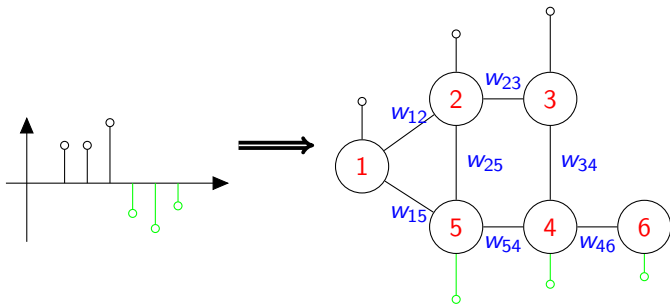
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- Signal values become node features. Why? What's the advantage? / Les valeurs du signal deviennent les features du node. C'est quoi l'avantage?
- This enables us to explicitly model specific dependence structures, and it's a good representation for irregular signals.
 - ▶ Ça nous permet de modéliser des structures des dépendances spécifiques, et est une bonne manière de modéliser des signaux irréguliers.

How to represent a graph though?

- We understand that $\mathcal{G} = \{V, E\}$ defines a graphs.
 - ▶ On comprend que les ensembles V, E définissent un graph complètement. Mais comment est-ce qu'on représente un graph numériquement?

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 - ▶ Les graphes undirecteds ont des matrices adjacency symmetriques.
- We will pack the node values in a vector $\mathbf{v} \in \mathbb{R}^N$. / On mets les features pour chaque node dans un vecteur $\mathbf{v}$.
 - ▶ $\mathbf{v}_i$ gives the feature value of node i . $\mathbf{v}_i$ donne le valeur du feature du node i .

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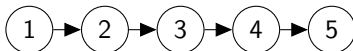
Graph Neural Networks

Examples

■ Undirected Path Graph

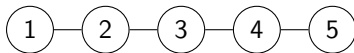


■ Directed Path Graph



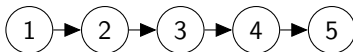
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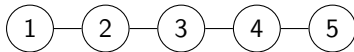
$$A = \begin{matrix} & \begin{matrix} \text{to} \\ \begin{matrix} 0 & 1 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 & 0 \end{matrix} \end{matrix} \\ \begin{matrix} \text{from} \\ \end{matrix} \end{matrix}$$

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$$A = \begin{matrix} & \begin{matrix} \text{to} \\ \begin{matrix} 1 & 2 & 3 & 4 & 5 \end{matrix} \end{matrix} \\ \begin{matrix} \text{from} \\ \begin{matrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \end{matrix} \end{matrix} & \begin{bmatrix} 0 & 1 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 & 0 \end{bmatrix} \end{matrix}$$

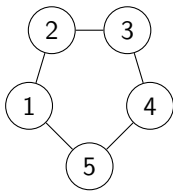
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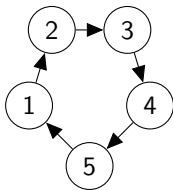
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Examples

■ Undirected Ring Graph

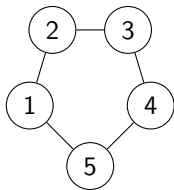


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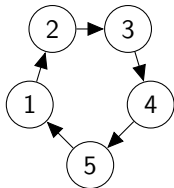
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$$A = \begin{matrix} & \begin{matrix} \text{to} \\ \begin{matrix} 0 & 1 & 0 & 0 & 1 \\ 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 1 \\ 1 & 0 & 0 & 1 & 0 \end{matrix} \end{matrix} \\ \begin{matrix} \text{from} \\ \end{matrix} \end{matrix}$$

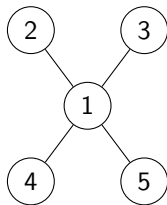
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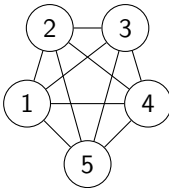
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More Examples

■ Undirected Star Graph

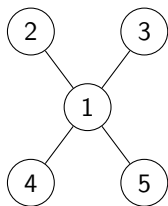


■ Undirected Fully Connected Graph



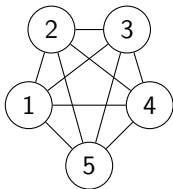
More Examples

■ Undirected Star Graph



$$A = \begin{matrix} & \begin{matrix} \text{to} \\ 0 & 1 & 1 & 1 & 1 \end{matrix} \\ \begin{matrix} \text{from} \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \end{matrix} & \end{matrix}$$

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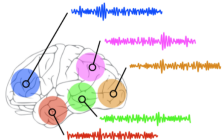
Real-World Examples

- Social Network Graph / Graphe d'un réseau sociale



Vertices: 1000 Twitter/X Users/Utilisateurs, **Edges:** Follower/not,
Node Features: How many times did they tag IEEE MLSP 2023.

- Brain Measurements / Mésurements du cerveau



Vertices: Different regions , **Edges:** Structural Connectivity,
Node Features: Brain activity measured as a 1d signal.

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Graph Signal Processing

- How do we work with such representations? Comment est-ce qu'on travaille avec tel représentations?
 - ▶ Graph Signal Processing
- Classical DSP assumes 'regular' data (It's assuming a graph). / DSP classique suppose une régularité dans les données.

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- Also, GSP enables learning over graphs. / On peut aussi apprendre des modèles sur des graphes.

New things to worry about

- Classical Signal Processing
 - ▶ Time / Pixel Domain
 - ▶ We model relationships of samples laid on a regular grid / On modélise des relations sur un grille régulière.
- Frequency Domain
 - ▶ Fourier Transform / DCT
- How do we move from spatial to graph domain? / Comment on va aller du domain spatial à la domaine de graphe?
 - ▶ We will use the Graph Laplacian L . / On va utiliser la graph laplacian L .
- Graph Signal Processing
 - ▶ The graph domain.
 - ▶ Can model relationships described using an adjacency matrix. / On peut modéliser des relations plus général défini par une matrice d'adjacency.
- Graph Spectral Domain
 - ▶ Graph Fourier Transform

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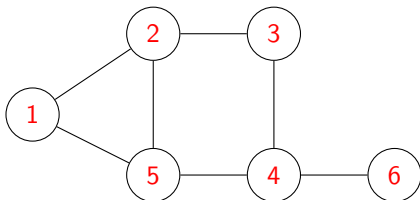
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The Graph Laplacian

- Consider this graph, with all weights equal to 1 / Considérons ce graph avec les poids égaux à 1.

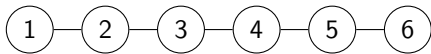


- $L := D - A$

Graph Laplacian		Degree Matrix		Adjacency Matrix
$\begin{bmatrix} 2 & -1 & 0 & 0 & -1 & 0 \\ -1 & 3 & -1 & 0 & -1 & 0 \\ 0 & -1 & 2 & -1 & 0 & 0 \\ 0 & 0 & -1 & 3 & -1 & -1 \\ -1 & -1 & 0 & -1 & 3 & 0 \\ 0 & 0 & 0 & -1 & 0 & 1 \end{bmatrix}$	$=$	$\begin{bmatrix} 2 & 0 & 0 & 0 & 0 & 0 \\ 0 & 3 & 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 0 & 0 & 0 \\ 0 & 0 & 0 & 3 & 0 & 0 \\ 0 & 0 & 0 & 0 & 3 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$	$-$	$\begin{bmatrix} 0 & 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 1 \\ 1 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \end{bmatrix}$
L		$D = \text{diag}(1^\top W)$		A

But, what is this graph Laplacian?

■ Undirected Path Graph



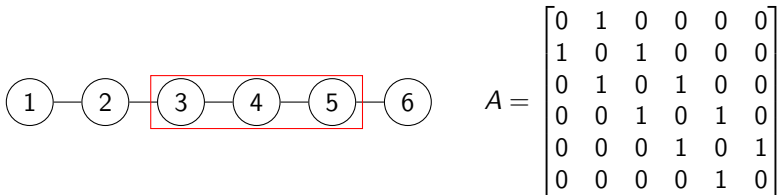
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■ The Laplacian

$$\begin{array}{ccc} \text{Graph Laplacian} & \text{Degree Matrix} & \text{Adjacency Matrix} \\ \begin{bmatrix} 1 & -1 & 0 & 0 & 0 & 0 \\ -1 & 2 & -1 & 0 & 0 & 0 \\ 0 & -1 & 2 & -1 & 0 & 0 \\ 0 & 0 & -1 & 2 & -1 & 0 \\ 0 & 0 & 0 & -1 & 2 & -1 \\ 0 & 0 & 0 & 0 & -1 & 1 \end{bmatrix} & = & \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 0 & 0 & 0 \\ 0 & 0 & 0 & 2 & 0 & 0 \\ 0 & 0 & 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix} \\ L & D = \text{diag}(1^\top W) & - \\ & & \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & 0 \end{bmatrix} \\ & & A \end{array}$$

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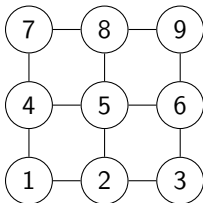


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L		$D = \text{diag}(1^\top W)$		A

This looks like the second derivative operator! (Discrete approximation to 2nd gradient) / C'est le noyau Laplacien, une approximation à la deuxième dérivée.

■ Undirected Path Graph



■ The Laplacian

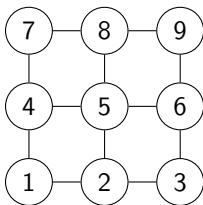
$$\begin{bmatrix}
 2 & -1 & 0 & -1 & 0 & 0 & 0 & 0 & 0 \\
 -1 & 3 & -1 & 0 & -1 & 0 & 0 & 0 & 0 \\
 0 & -1 & 2 & 0 & 0 & -1 & 0 & 0 & 0 \\
 -1 & 0 & 0 & 3 & -1 & 0 & -1 & 0 & 0 \\
 0 & -1 & 0 & -1 & 4 & -1 & 0 & -1 & 0 \\
 0 & 0 & -1 & 0 & -1 & 3 & 0 & 0 & -1 \\
 0 & 0 & 0 & -1 & 0 & 0 & 2 & -1 & 0 \\
 0 & 0 & 0 & 0 & -1 & 0 & -1 & 3 & -1 \\
 0 & 0 & 0 & 0 & 0 & -1 & 0 & -1 & 2
 \end{bmatrix}
 \begin{matrix}
 L
 \end{matrix}$$

$$D = \text{diag}(1^T W)$$

$$\begin{bmatrix}
 2 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
 0 & 3 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
 0 & 0 & 2 & 0 & 0 & 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 3 & 0 & 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 & 4 & 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 & 0 & 3 & 0 & 0 & 0 \\
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 \end{bmatrix}
 \begin{matrix}
 D = \text{diag}(1^T W)
 \end{matrix}$$

$$A$$

■ Undirected Path Graph



■ The Laplacian

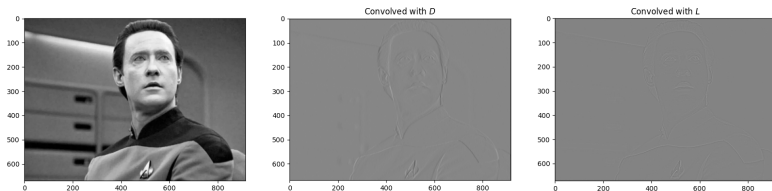
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 2 & -1 & 0 & -1 & 0 & 0 & 0 & 0 & 0 \\
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 0 & -1 & 2 & 0 & 0 & -1 & 0 & 0 & 0 \\
 -1 & 0 & 0 & 3 & -1 & 0 & -1 & 0 & 0 \\
 \hline
 0 & -1 & 0 & -1 & 4 & -1 & 0 & -1 & 0 \\
 0 & 0 & -1 & 0 & -1 & 3 & 0 & 0 & -1 \\
 0 & 0 & 0 & -1 & 0 & 0 & 2 & -1 & 0 \\
 0 & 0 & 0 & 0 & -1 & 0 & -1 & 3 & -1 \\
 0 & 0 & 0 & 0 & 0 & -1 & 0 & -1 & 2
 \end{bmatrix}
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 2 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
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 0 & 0 & 0 & 3 & 0 & 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 & 4 & 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 & 0 & 3 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 & 0 & 0 & 2 & 0 & 0 \\
 0 & 0 & 0 & 0 & 0 & 0 & 0 & 3 & 0 \\
 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 2
 \end{bmatrix}
 \begin{bmatrix}
 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\
 1 & 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 \\
 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\
 1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 & 0 \\
 0 & 1 & 0 & 1 & 0 & 1 & 0 & 1 & 0 \\
 0 & 0 & 1 & 0 & 1 & 0 & 0 & 0 & 1 \\
 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 \\
 0 & 0 & 0 & 0 & 1 & 0 & 1 & 0 & 1 \\
 0 & 0 & 0 & 0 & 0 & 1 & 0 & 1 & 0
 \end{bmatrix}$$

L
 $D = \text{diag}(1^T W)$
 A

This looks like the second derivative operator! (Discrete approximation to 2nd gradient) / C'est le noyau Laplacien, une approximation à la deuxième dérivée.

Laplacian Operator on Images

Data is back!

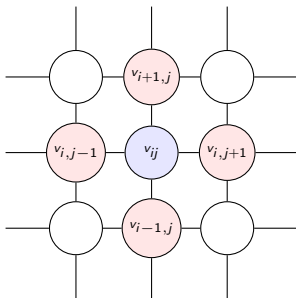


$$D = [1, -1] \quad L = \begin{bmatrix} 0 & -1 & 0 \\ -1 & 4 & -1 \\ 0 & -1 & 0 \end{bmatrix}$$

L is an edge detector here.

The Graph Laplacian Properties

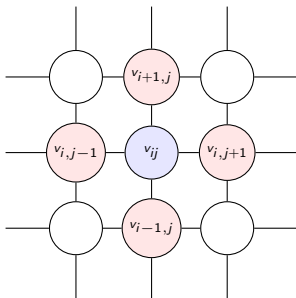
- We approximate the Laplace operator on the graph with Graph Laplacian / On approxime l'opérateur Laplace avec le Graph Laplacian.



- For undirected graphs L is symmetric. / Pour des graphs undirected L est symétrique.
- Off diagonals are non-positive. / Les non-diagonales sont non-positives.
- Rows add up to zero. / Les lignes s'ajoutent à zéro.

The Graph Laplacian Properties

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- For undirected graphs L is symmetric. / Pour des graphs undirected L est symétrique.
- Off diagonals are non-positive. / Les non-diagonales sont non-positives.
- Rows add up to zero. / Les lignes s'ajoutent à zéro.
- There's also the normalized Laplacian, $L_{\text{norm}} = D^{-1/2}(D - A)D^{-1/2}$, but we'll stick to L for now. / Il existe aussi la Laplacienne normalisé.

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The Graph Fourier Transform

- Given a Graph G containing a signal s , / Étant donné le graphe qui contient un signal s .
- Get Graph Laplacian L . / Obtiens la Laplacienne L .
- Do the eigenvalue decomposition on L . / Fait la décomposition éigen de L :

$$L = V\Lambda V^T$$

- Transform the graph signal / Transforme le signal dans le graphe,

$$S = V^T s$$

What does this mean?

- You can show that / On peut montrer que,

$$u^\top L u = \frac{1}{2} \sum_{i,j=1}^N \underbrace{w_{ij}}_{Adj.} \underbrace{(u_i - u_j)^2}_{\text{local variation}}$$

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- What maximizes this measure of variation? / Que peut maximizer cette mesure de variation?
- $\max_u u^\top Lu$ s.t. $u^\top u = 1$. What are these optimal u 's? / Que sont ces u 's optimales?

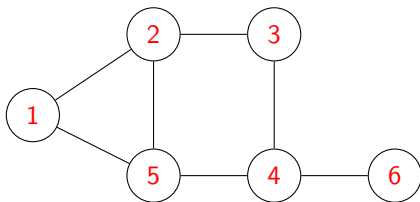
What does this mean?

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- What maximizes this measure of variation? / Que peut maximizer cette mesure de variation?
- $\max_u u^\top L u$ s.t. $u^\top u = 1$. What are these optimal u 's? / Que sont ces u 's optimales?
- Eigenvectors of L ! / Vecteurs propres de L !
- Also, note that larger $u^\top L u$ is, higher frequency we have in the signal u . / Notez que plus $u^\top L u$ est large, plus le signal dans u est de haute fréquence.

Example



$$\begin{bmatrix} 2 & -1 & 0 & 0 & -1 & 0 \\ -1 & 3 & -1 & 0 & -1 & 0 \\ 0 & -1 & 2 & -1 & 0 & 0 \\ 0 & 0 & -1 & 3 & -1 & -1 \\ -1 & -1 & 0 & -1 & 3 & 0 \\ 0 & 0 & 0 & -1 & 0 & 1 \end{bmatrix}$$

x	$x^\top Lx$
$[1, 1, 1, 1, 1, 1]$	0
$[0, 0, 1, 1, 0, 0]$	3
$[1, 0, 1, 0, 1, 0]$	5

Low and High Frequency Graph Signals

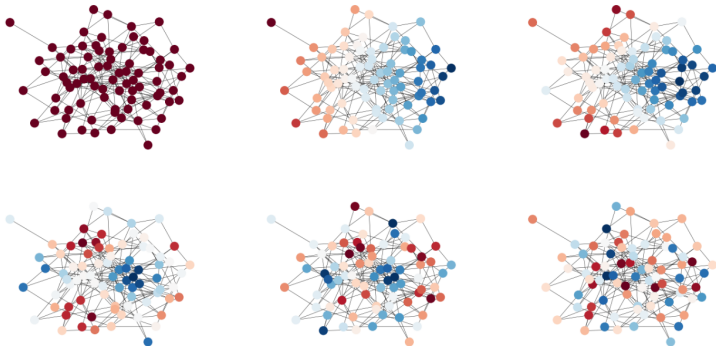
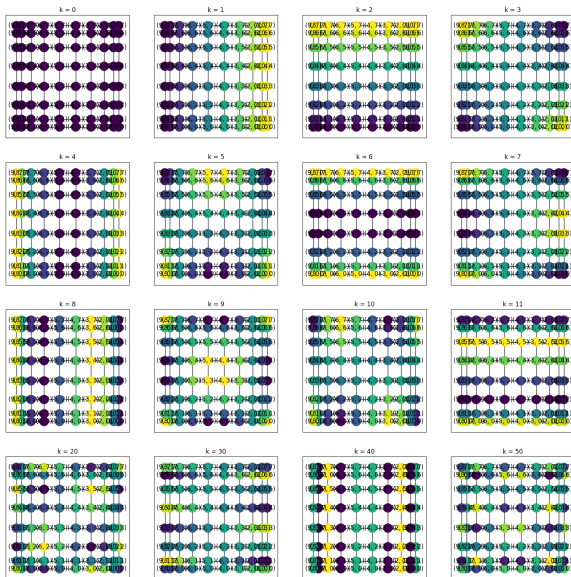
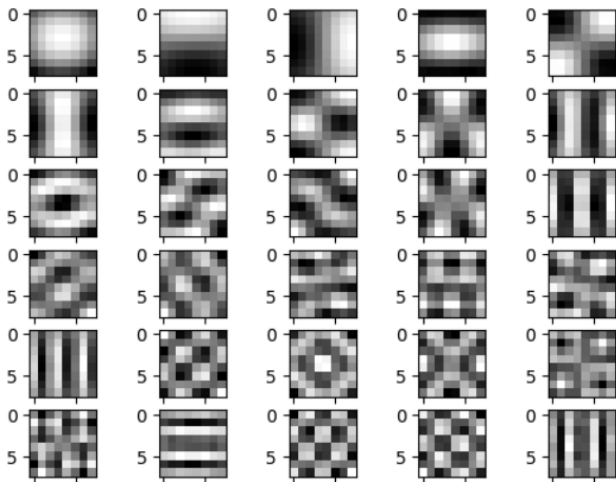


Image taken from UIUC MLSP class

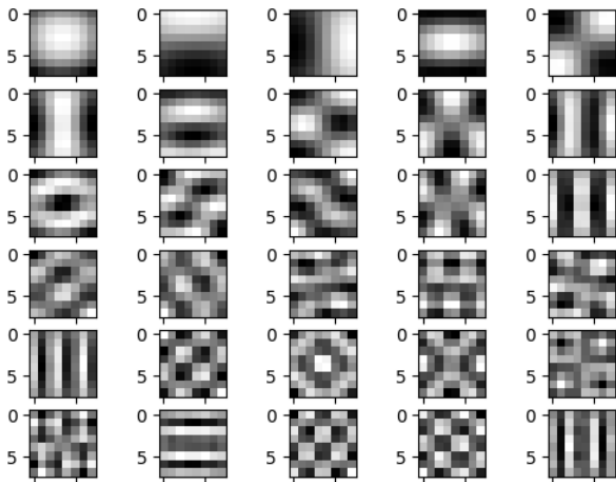
Grid Graph



Do you remember this?



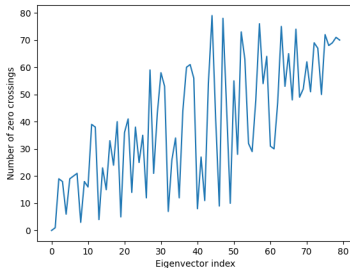
Do you remember this?



- It seems we were learning eigenvectors that correspond to a grid graph!
 - ▶ On apprendait des vecteurs propres qui correspondent à un graphe grille!

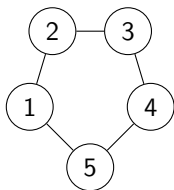
Eigenvalues as a measure of frequency

- The eigenvalues measure graph frequency
 - ▶ Les valeurs propres mesurent la fréquence de chaque base
- We can rank the eigenvectors by their eigenvalues / On peut mettre les vecteurs propres par leur valeurs propres
 - ▶ First eigenvectors are slow / change slowly. Les premiers vecteurs propres changent lentement
- The number of zero crossings for each eigenvector / le nombre de croisements zeros pour chaque vecteur propre:



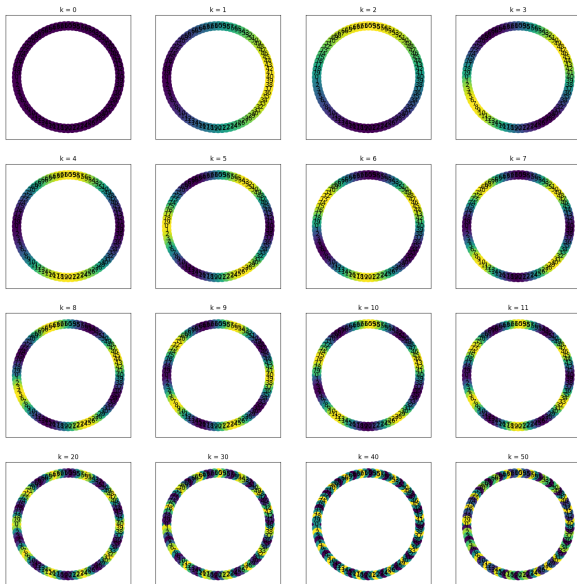
Special Case: DFT

■ Undirected Ring Graph



$$A = \begin{matrix} & \begin{matrix} \text{to} \\ \begin{matrix} 0 & 1 & 0 & 0 & 1 \\ 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 1 \\ 1 & 0 & 0 & 1 & 0 \end{matrix} \end{matrix} \\ \begin{matrix} \text{from} \\ \begin{matrix} 0 \\ 1 \\ 0 \\ 0 \\ 1 \end{matrix} \end{matrix} \end{matrix} \begin{bmatrix} 0 & 1 & 0 & 0 & 1 \\ 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 1 \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix}$$

- Eigenvectors of L correspond to the Discrete Fourier Transform (DFT)! / Les vecteurs propres de L correspondent à DFT!



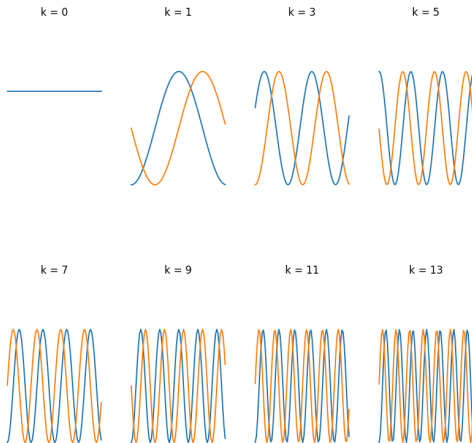
- Paired Sine / Cosine Bases,

$$u_k(n) = \exp(j2\pi kn/N)$$

DFT Bases

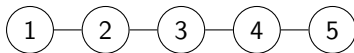
■ Paired Sine / Cosine Bases,

$$u_k(n) = \exp(j2\pi kn/N) = \cos(2\pi kn/N) + j \sin(2\pi kn/N)$$



Special Case 2, Discrete Cosine Transform

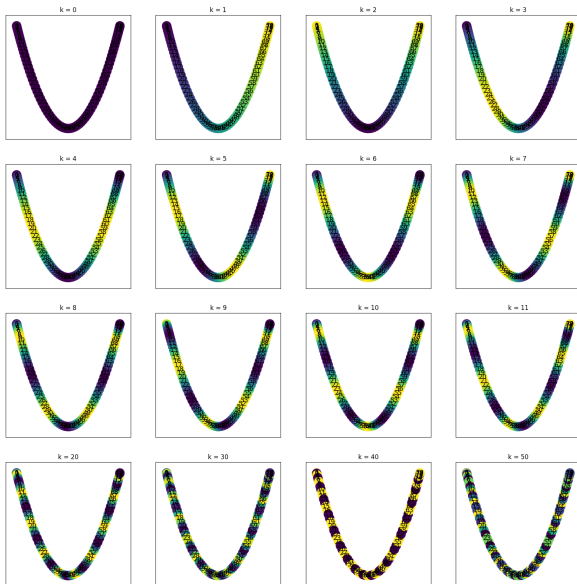
■ Undirected Path Graph



$$A = \begin{matrix} & \begin{matrix} \text{to} \\ \begin{matrix} 1 & 2 & 3 & 4 & 5 \end{matrix} \end{matrix} \\ \begin{matrix} \begin{matrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \end{matrix} \\ \text{from} \end{matrix} & \begin{bmatrix} 0 & 1 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 & 0 \end{bmatrix} \end{matrix}$$

■ Eigenvectors of the Graph Laplacian will correspond to the DCT bases!

- ▶ Les vecteurs propres du Laplacien correspondent aux bases DCT!



DCT-Type2 Bases

- Paired Sine / Cosine Bases,

$$u_{m,k}(n) \propto \cos((m + 0.5)k\pi/N)$$

.

DCT-Type2 Bases

■ Paired Sine / Cosine Bases,

$$u_{m,k}(n) \propto \cos((m + 0.5)k\pi/N)$$

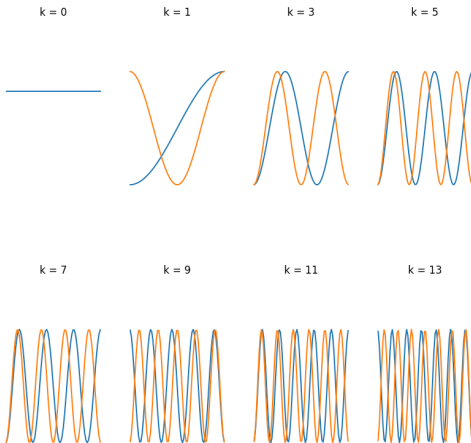


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Imposing a Graph

- Recap so far / Sommaire de ce qu'on a vu:
 - ▶ Graphs are collection of nodes and edges. / Un graphe est une collection des nodes et des edges.
 - ▶ A node is defined by an adjacency matrix A / Un graphe est défini par un adjacency matrix A .
 - ▶ Graph Laplacian $L = D - A$.
 - ▶ Is used to compute the Graph Fourier Transform. / Est utilisé pour calculer le Graph Fourier Transform.
 - ▶ This generalizes the classical Fourier Transform / Ça généralise le Fourier Transforme.
- We understand that standard SP assumes an underlying graph / Tout ça nous montre que le SP classique suppose un graphe.
 - ▶ Can we adjust the graph so that it's more suitable? / Peut-on ajuster le graph pour qu'il est plus ajusté?

Defining a Graph from a Signal

- We can define adjacency based on spatial location / On peut définir le voisinage en utilisant la localisation spatiale, temporelle

$$A_{ij}^t = \exp(-\alpha \|t_i - t_j\|)$$

- Or, we can define an adjacency based on sample values / Ou, on peut définir le voisinage en utilisant les valeurs
 - ▶ Do you remember this from somewhere else? / Souvenez-vous de ça d'ailleurs?

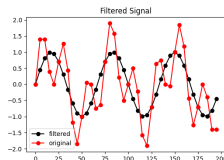
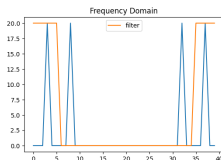
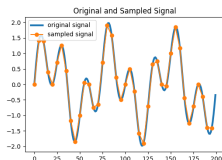
$$A_{ij}^x = \exp(-\beta \|x_i - x_j\|)$$

- We can define an overall adjacency matrix / On peut définir une matrice de voisinage ultime:

$$A = \gamma A^t + (1 - \gamma) A^x$$

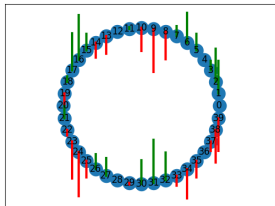
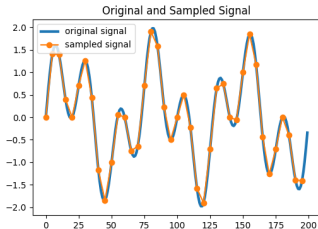
Classical filtering

■ $x_t = \cos(3\omega t) + \cos(8\omega t)$

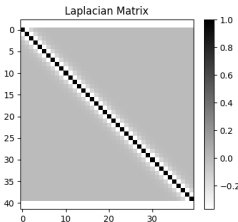
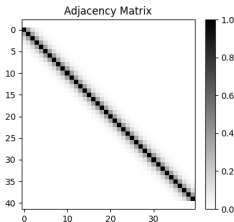


Let's do the same thing with Graphs

- Now we will define the same signal on a graph / On définit maintenant le meme signal sur un graphe

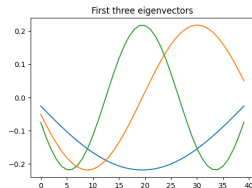
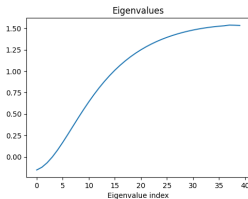
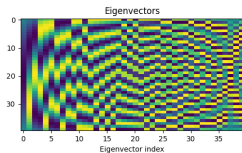


- Adjacency matrix, and the Laplacian (for a cycle graph)
 - $A_{ij} = \exp(-\alpha \|t_i - t_j\|)$



Step 1: Obtain the frequency bases of L

■ $L = V\Lambda V^T$



Graph Filtering Steps

- Transform onto the graph Laplacian eigenvectors.

$$X = \underbrace{V^T}_{\text{Eigenvec.}} \underbrace{x}_{\text{signal}}$$

Graph Filtering Steps

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$$\hat{x} = VZ$$

Graph Filtering Steps

- Transform onto the graph Laplacian eigenvectors.

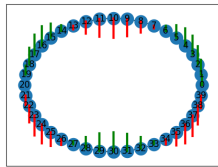
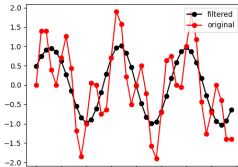
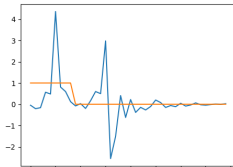
$$X = \underbrace{V^T}_{\text{Eigenvec.}} \underbrace{x}_{\text{signal}}$$

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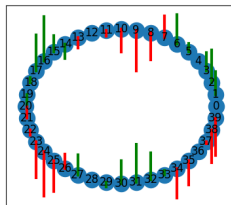
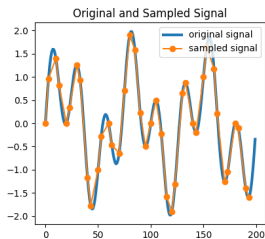
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$$\hat{x} = VZ$$

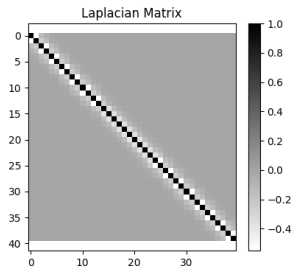
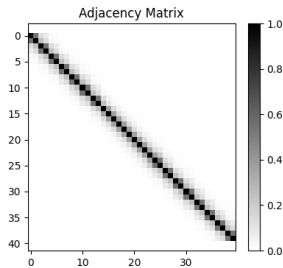


Nothing new with this, so why?

- What if the sample rate was not as regular / Et si le taux d'échantillonnage n'était pas si régulier?
- We can use a corresponding irregular graph maybe? / On peut utiliser la graph qui correspond?

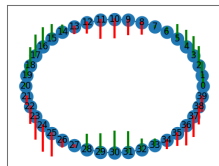
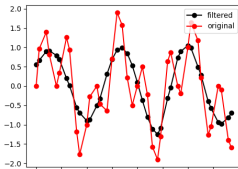
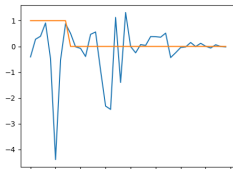


The new graph structure



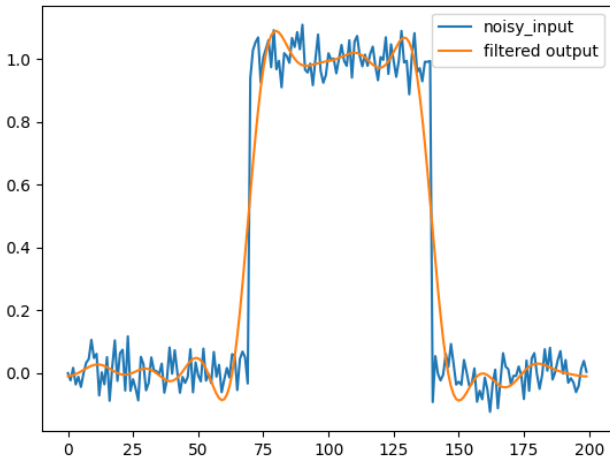
Non Uniform Graph Filtering

- We can still apply the same process as before / On peut encore appliquer le meme processus



Encoding context from a signal

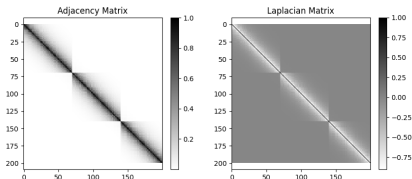
- Consider this noisy signal with steep edges / Considerons ce signal avec des sautes



Using the signal in the adjacency

- Can we somehow encode that closer values are similar? / Peut-on encoder que les valeurs qui sont proches sont plus similaires?
- Adjacency matrix:

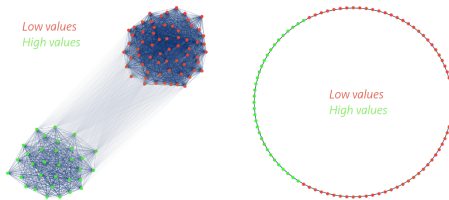
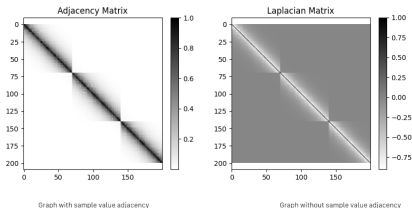
$$A_{ij} = \exp(-\alpha \|t_i - t_j\| - \beta \|x_i - x_j\|)$$



Using the signal in the adjacency

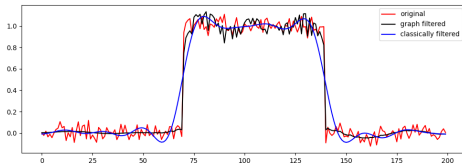
- Can we somehow encode that closer values are similar? / Peut-on encoder que les valeurs qui sont proches sont plus similaires?
- Adjacency matrix:

$$A_{ij} = \exp(-\alpha \|t_i - t_j\| - \beta \|x_i - x_j\|)$$



Edge preserving filter

- We can see that the graph filtering better preserves the edges / On voit que le filtre de graph mieux protège les sautes.



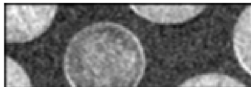
Edge preserving 2D example

- We can also apply the same thing on 2D signals / On peut appliquer la meme affaire sur des signaux 2D aussi.

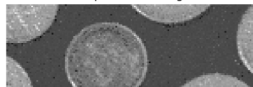
Input image



Time-filtered image



Graph-filtered image



Defining Graphs from Data

- We already did this! / On a déjà fait ça
 - ▶ Eigendecomposition on an affinity matrix = KPCA/MDS/ISOMAP.
 - ▶ Clustering the eigenvectors = Spectral Clustering.

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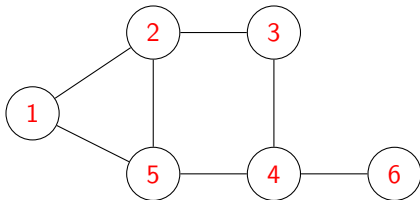
Graph Signal Processing in Action

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Filtering in the graph spatial domain

- In regular signals we have the frequency domain / time domain filtering duality. / Dans les signaux réguliers on a une dualité entre filtrage dans le domaine de temps / domaine de fréquence.
- Filtering in the time domain is defined by convolution which uses shifts. Filtrage dans le domaine de temps utilise des shifts.
- We can also define a shift operator on graphs. / On define a shift operator over graphs



$$S = \begin{bmatrix} 1 & 1 & 0 & 0 & 1 & 0 \\ 1 & 1 & 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 & 0 & 1 \end{bmatrix} = I + A$$

Graph Filtering / Convolution

- Graph filtering definition: $h * x = \sum_k h_k S^k x$
- For instance for $h = [1, 1, 0.5]^\top$, $x = [-1, 2, 0, 0, 0, 0]^\top$

$$S = \begin{bmatrix} 1 & 1 & 0 & 0 & 1 & 0 \\ 1 & 1 & 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 & 0 & 1 \end{bmatrix} = I + A$$

$$Sx = [1, 1, 2, 0, 1, 0]^\top, \quad S^2x = [3, 5, 3, 3, 3, 0]^\top$$

$$y = h_0 x + h_1 Sx + h_2 S^2x = [1, 5, 2.5, 1.5, 2, 0]^\top$$

Graph Filtering / Convolution

- Graph filtering definition: $h * x = \sum_k h_k S^k x$
- For instance for $h = [1, 1, 0.5]^\top$, $x = [-1, 2, 0, 0, 0, 0]^\top$

$$S = \begin{bmatrix} 1 & 1 & 0 & 0 & 1 & 0 \\ 1 & 1 & 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 & 0 & 1 \end{bmatrix} = I + A$$

$$Sx = [1, 1, 2, 0, 1, 0]^\top, \quad S^2x = [3, 5, 3, 3, 3, 0]^\top$$

$$y = h_0 x + h_1 Sx + h_2 S^2x = [1, 5, 2.5, 1.5, 2, 0]^\top$$

- Notice that S defines a kernel with which we convolve! / Notez que S implique une sorte de noyau de convolution!

To summarize

- Signals can be defined as graphs / Signaux peut-être défini comme des graphs.
 - ▶ It enables us to represent more structured sample relations / Ça nous permet d'établir des relations plus structurées entre les échantillons.
- We can define analogs to classical DSP / On peut définir des analogues aux DSP.
- Now, let's briefly mention that we can do ML also! / On peut faire du ML aussi!

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Graph Signal Processing in Action

Graph Convolution

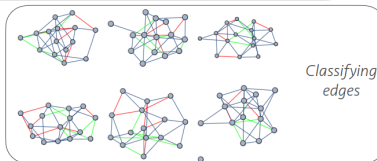
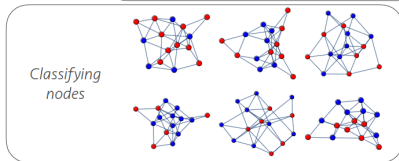
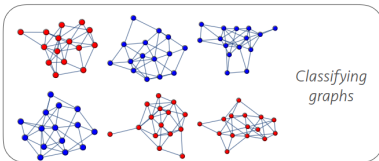
Graph Neural Networks

Graph Neural Networks

- Neural Nets that operate on graphs. / Neural Nets qui fonctionnent sur des graphs.
 - ▶ Using the graph shift matrix, we can define CNNs, RNNs.. / On peut définir des CNNs / RNNs en utilisant l'opérateur graph shift.
- Useful for things like / Utile pour des choses comme:
 - ▶ Molécules, social graphs, mesh representations, LIDAR, ...
- Hot topic / Je ne suis pas expert du tout!

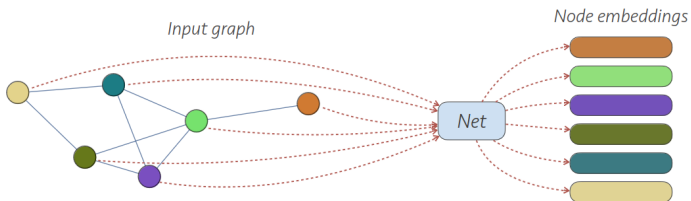
Types of Graph Level Processing

- Graph Level Processing, e.g. classifying a molecule
- Node Level Processing, e.g. LIDAR pixel classification
- Edge Level Processing e.g. Relationship classification in a social network



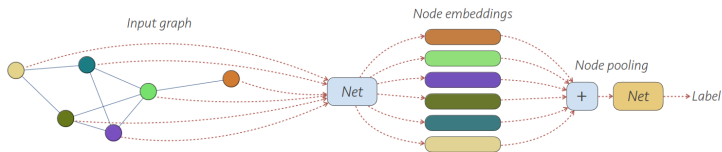
A very naive Graph Neural Network

- We can embed the nodes only / On embed les nodes seulement
 - ▶ Like you can do on your spectra in HW2-Q2 :)



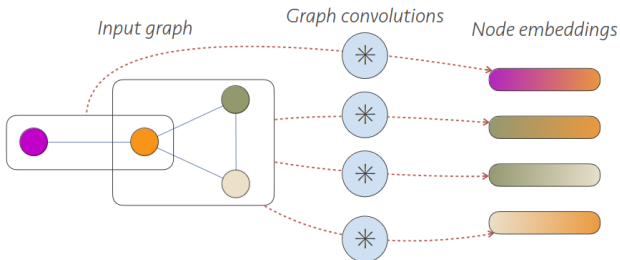
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Adding the graph structure

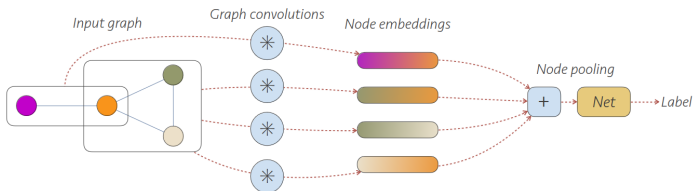
- We can also use graph convolutions to combine neighboring nodes when computing the node embeddings / On peut aussi inclure des convolutions graphes quand on calcule les node embeddings.
 - ▶ This enables us to model the graph structure / Ça nous permet de modéliser la structure de la graphe.



- Instead of using CNNs, it's possible to use RNNs / Attention Models, all that / Au lieu d'utiliser des CNNs, c'est possible d'utiliser des RNNs, modèles d'attention.

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- The graph convolutions

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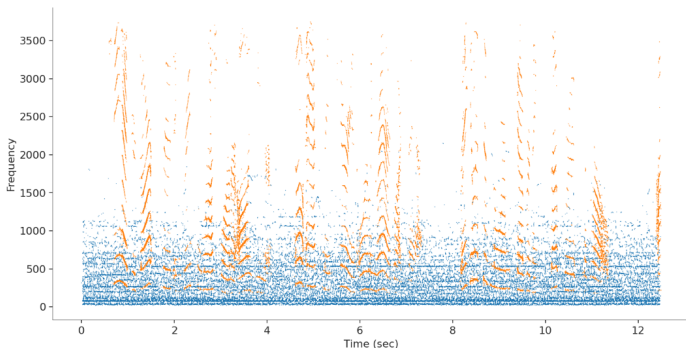
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- Note that if we want to express the transformation above with matrix multiplications, we can do the following: / On peut faire la meme chose avec des multiplications de matrices.

$$h^k = \widetilde{W^k} \bar{A} h^{k-1} / (1^\top A)$$

where $\bar{A} = A + I$, A being the adjacency matrix of the graph (size node by node), I is the identity matrix, and $\widetilde{W^k}$ combines W^k and B^k .

Audio Example

- Using point clouds for a spectrogram / Nuage de points pour un spectrogram (Look up re-assigned spectrograms)



- Instead of having series of vectors, we have a point cloud / on a un nuage de points au lieu de vecteurs: $C = [(f_1, t_1), (f_2, t_2), \dots, (f_N, t_N)]$.
- The paper (see the reading list) claims that training is faster, model is smaller, performance is better. (Best paper award in WASPAA 2021). / Le papier dit que l'entraînement est plus rapide, modèle est plus petit, et la performance est mieux.

Recap

- Signals are graphs! It's better to be aware of that to be able to generalize. / Les signaux sont des graphs en tout cas! Si on voit ça, on peut generaliser.
- Signal processing with Graph Perspective / Traitement du Signal avec un Perspective de Graphe
 - ▶ The Graph Fourier Transform
- Graph Neural Networks
 - ▶ Useful in many structured data domains (e.g. drug design) / Utile dans plusieurs données avec structure

Reading Material

- Graph Signal Processing:
<https://arxiv.org/pdf/1712.00468.pdf>
- GNN tutorial:
<https://distill.pub/2021/understanding-gnns/>
- Audio point cloud GNN stuff:
<https://arxiv.org/pdf/2105.02469.pdf>

Next and last week

- I will talk about speech/audio topics. Je vais parler sur speech/audio.