

IFT 4030/7030,
Machine Learning for Signal Processing
**Week11: Graphs in Signal Processing
and Machine Learning**

Cem Subakan



UNIVERSITÉ
LAVAL



Mila

- Mathieu a donné quelques feedbacks pour vos projets. Je vais essayer de faire la même chose. Si vous avez des doutes, SVP prenez un rendez-vous avec moi / TAs!
 - ▶ Mathieu gave some feedback for the projects. I will try to do the same also. If you have doubts, please let me / TAs know!
- Le dernier lab est en vendredi. SVP soyez là!
 - ▶ The last lab is this friday. Please be there!

Today's Lecture

- Graphs!
- Using Graphs instead of vectors / matrices
 - ▶ On va utiliser des graphs au lieu de vecteurs / matrices
- Graph Signal Processing Basics
 - ▶ Les bases du traitement du signal avec des graphs
- Graph Machine Learning
 - ▶ De l'apprentissage automatique avec des graphs

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Graph Basics

Example Graphs

Graph Signal Processing

The Graph Laplacian

Graph Fourier Transform

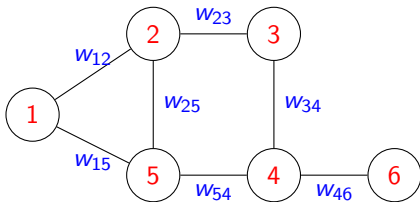
Graph Signal Processing in Action

Graph Convolution

Graph Neural Networks

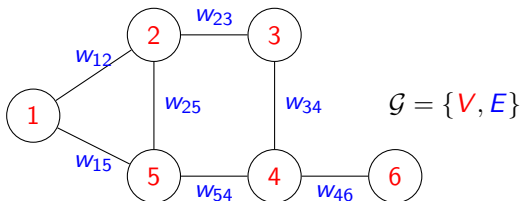
Graph

- A graph is a set of vertices (nodes) and edges.



Graph

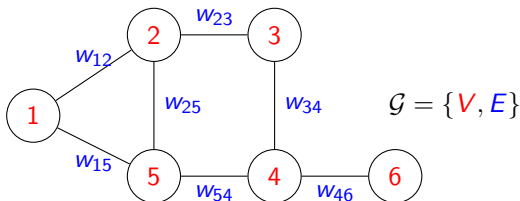
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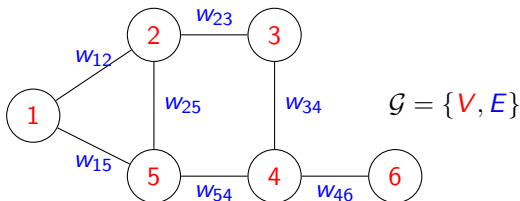
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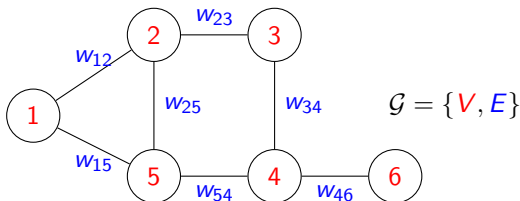
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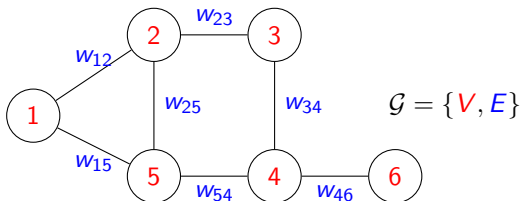
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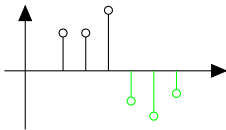
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- Graphs model **pairwise** relationships.
 - ▶ Les graphs modèle des relations **par paires**.

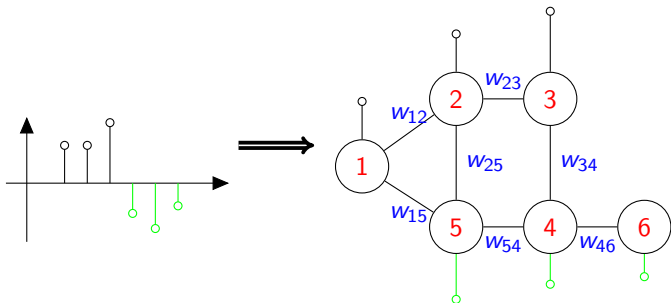
Representing a Signal as a Graph

- Associate each sample of the signal to a node. / On va associer chaque échantillon du signal avec un vertex.
 - ▶ Example: $x = [0.5, 0.5, 0.8, -0.4, -0.6, -0.3]$.



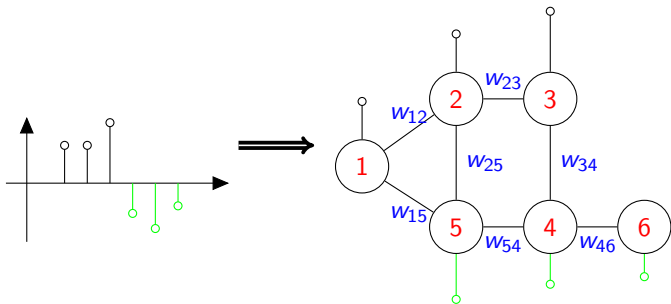
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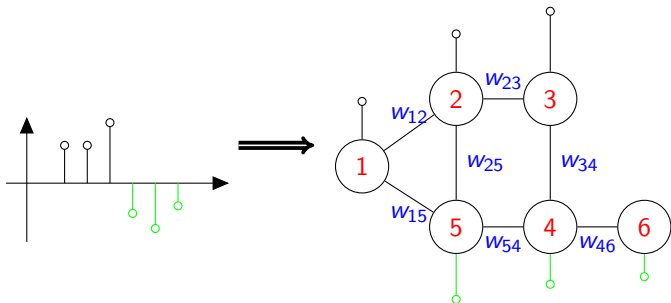
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- Signal values become node features. Why? What's the advantage? / Les valeurs du signal devient les features du node. C'est quoi l'avantage?
- This enables us to explicitly model specific dependence structures, and it's a good representation if irregular signals.
 - ▶ Ça nous permet de modéliser des structures des dépendences spécifiques, et est une bonne manière de modéliser des signaux irregulaires.

How to represent a graph though?

- We understand that $\mathcal{G} = \{V, E\}$ defines a graphs.
 - ▶ On comprend que les ensembles V, E définissent un graph complètement. Mais comment est-ce qu'on représente un graph numériquement?

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 - ▶ Les graphes undirecteds ont des matrices adjacency symmetriques.
- We will pack the node values in a vector $v \in \mathbb{R}^N$. / On mets les features pour chaque node dans un vecteur v .
 - ▶ v_i gives the feature value of node i . v_i donne le valeur du feature du node i .

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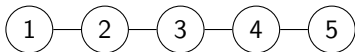
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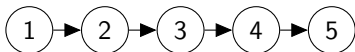
Graph Neural Networks

Examples

- Undirected Path Graph

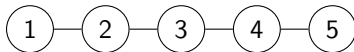


- Directed Path Graph



Examples

■ Undirected Path Graph



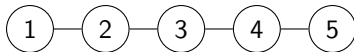
$$A = \begin{matrix} & \begin{matrix} \text{to} \\ \begin{bmatrix} 0 & 1 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 & 0 \end{bmatrix} \\ \text{from} \end{matrix} \end{matrix}$$

■ Directed Path Graph



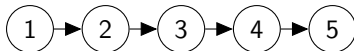
Examples

■ Undirected Path Graph



$$A = \begin{matrix} & \begin{matrix} \text{to} \\ 0 & 1 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 & 0 \end{matrix} \\ \begin{matrix} \text{from} \\ \left[\begin{array}{c} 0 \\ 1 \\ 0 \\ 0 \\ 0 \end{array} \right] \end{matrix} \end{matrix}$$

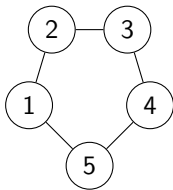
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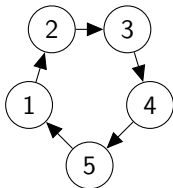
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Examples

■ Undirected Ring Graph

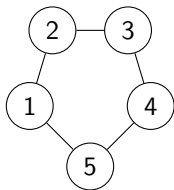


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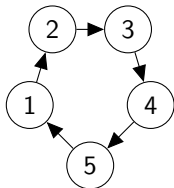
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$$A = \begin{matrix} & \begin{matrix} \text{to} \\ 0 & 1 & 0 & 0 & 1 \end{matrix} \\ \begin{matrix} \text{from} \\ 1 \\ 2 \\ 3 \\ 4 \\ 5 \end{matrix} & \begin{bmatrix} 0 & 1 & 0 & 0 & 1 \\ 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 1 \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix} \end{matrix}$$

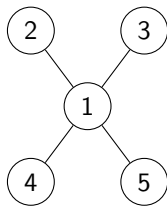
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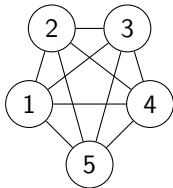
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More Examples

- Undirected Star Graph

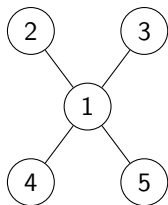


- Undirected Fully Connected Graph



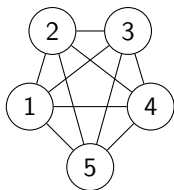
More Examples

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$$A = \begin{matrix} & \begin{matrix} \text{to} \\ 0 & 1 & 1 & 1 & 1 \end{matrix} \\ \begin{matrix} \text{from} \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \end{matrix} & \begin{bmatrix} 0 & 1 & 1 & 1 & 1 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \end{bmatrix} \end{matrix}$$

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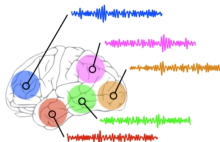
Real-World Examples

- Social Network Graph / Graphe d'un réseau sociale



Vertices: 1000 Twitter/X Users/Utilisateurs, **Edges:** Follower/not,
Node Features: How many times did they tag IEEE MLSP 2023.

- Brain Measurements / Mésurements du cerveau



Vertices: Different regions , **Edges:** Structural Connectivity,
Node Features: Brain activity measured as a 1d signal.

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Graph Signal Processing

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- Also, GSP enables learning over graphs. / On peut aussi apprendre des modèles sur des graphes.

New things to worry about

- Classical Signal Processing
 - ▶ Time / Pixel Domain
 - ▶ We model relationships of samples laid on a regular grid / On modélise des relations sur un grille régulière.
- Frequency Domain
 - ▶ Fourier Transform / DCT
- How do we move from spatial to graph domain? / Comment on va aller du domain spatial à la domaine de graphe?
 - ▶ We will use the Graph Laplacian L . / On va utiliser la graph laplacian L .
- Graph Signal Processing
 - ▶ The graph domain.
 - ▶ Can model relationships described using an adjacency matrix. / On peut modéliser des relations plus général défini par une matrice d'adjacency.
- Graph Spectral Domain
 - ▶ Graph Fourier Transform

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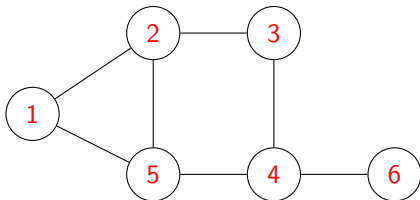
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The Graph Laplacian

- Consider this graph, with all weights equal to 1 / Considérons ce graph avec les poids égaux à 1.

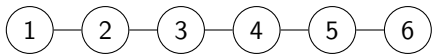


- $L := D - A$

Graph Laplacian	Degree Matrix	Adjacency Matrix
$\begin{bmatrix} 2 & -1 & 0 & 0 & -1 & 0 \\ -1 & 3 & -1 & 0 & -1 & 0 \\ 0 & -1 & 2 & -1 & 0 & 0 \\ 0 & 0 & -1 & 3 & -1 & -1 \\ -1 & -1 & 0 & -1 & 3 & 0 \\ 0 & 0 & 0 & -1 & 0 & 1 \end{bmatrix}$	$\begin{bmatrix} 2 & 0 & 0 & 0 & 0 & 0 \\ 0 & 3 & 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 0 & 0 & 0 \\ 0 & 0 & 0 & 3 & 0 & 0 \\ 0 & 0 & 0 & 0 & 3 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$	$\begin{bmatrix} 0 & 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 1 \\ 1 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \end{bmatrix}$
L	$D = \text{diag}(1^T W)$	A

But, what is this graph Laplacian?

■ Undirected Path Graph



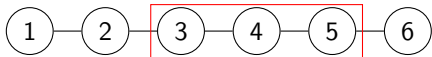
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■ The Laplacian

$$\begin{array}{ccc} \text{Graph Laplacian} & \text{Degree Matrix} & \text{Adjacency Matrix} \\ \begin{bmatrix} 1 & -1 & 0 & 0 & 0 & 0 \\ -1 & 2 & -1 & 0 & 0 & 0 \\ 0 & -1 & 2 & -1 & 0 & 0 \\ 0 & 0 & -1 & 2 & -1 & 0 \\ 0 & 0 & 0 & -1 & 2 & -1 \\ 0 & 0 & 0 & 0 & -1 & 1 \end{bmatrix} & = & \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 0 & 0 & 0 \\ 0 & 0 & 0 & 2 & 0 & 0 \\ 0 & 0 & 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix} \\ L & & D = \text{diag}(1^T W) \\ & & - \\ & & \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & 0 \end{bmatrix} \\ & & A \end{array}$$

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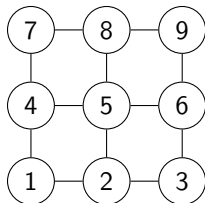
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This looks like the second derivative operator! (Discrete approximation to 2nd gradient) / C'est le noyau Laplacien, une approximation à la deuxième dérivée.

■ Undirected Path Graph

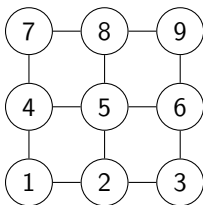


■ The Laplacian

$$\begin{bmatrix}
 2 & -1 & 0 & -1 & 0 & 0 & 0 & 0 & 0 \\
 -1 & 3 & -1 & 0 & -1 & 0 & 0 & 0 & 0 \\
 0 & -1 & 2 & 0 & 0 & -1 & 0 & 0 & 0 \\
 -1 & 0 & 0 & 3 & -1 & 0 & -1 & 0 & 0 \\
 0 & -1 & 0 & -1 & 4 & -1 & 0 & -1 & 0 \\
 0 & 0 & -1 & 0 & -1 & 3 & 0 & 0 & -1 \\
 0 & 0 & 0 & -1 & 0 & 0 & 2 & -1 & 0 \\
 0 & 0 & 0 & 0 & -1 & 0 & -1 & 3 & -1 \\
 0 & 0 & 0 & 0 & 0 & -1 & 0 & -1 & 2
 \end{bmatrix}
 \begin{bmatrix}
 2 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
 0 & 3 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
 0 & 0 & 2 & 0 & 0 & 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 3 & 0 & 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 & 4 & 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 & 0 & 3 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 & 0 & 0 & 2 & 0 & 0 \\
 0 & 0 & 0 & 0 & 0 & 0 & 0 & 3 & 0 \\
 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 2
 \end{bmatrix}
 \begin{bmatrix}
 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\
 1 & 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 \\
 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\
 1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 & 0 \\
 0 & 1 & 0 & 1 & 0 & 1 & 0 & 1 & 0 \\
 0 & 0 & 1 & 0 & 1 & 0 & 0 & 0 & 1 \\
 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 \\
 0 & 0 & 0 & 0 & 1 & 0 & 1 & 0 & 1 \\
 0 & 0 & 0 & 0 & 0 & 1 & 0 & 1 & 0
 \end{bmatrix}$$

L
 $D = \text{diag}(\mathbf{1}^T W)$
 A

■ Undirected Path Graph



■ The Laplacian

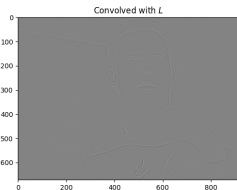
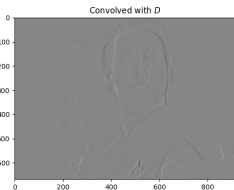
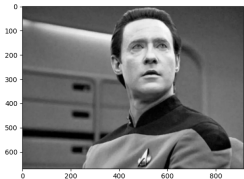
$$\begin{bmatrix}
 2 & -1 & 0 & -1 & 0 & 0 & 0 & 0 & 0 \\
 -1 & 3 & -1 & 0 & -1 & 0 & 0 & 0 & 0 \\
 0 & -1 & 2 & 0 & 0 & -1 & 0 & 0 & 0 \\
 -1 & 0 & 0 & 3 & -1 & 0 & -1 & 0 & 0 \\
 0 & -1 & 0 & -1 & 4 & -1 & 0 & -1 & 0 \\
 0 & 0 & -1 & 0 & -1 & 3 & 0 & 0 & -1 \\
 0 & 0 & 0 & -1 & 0 & 0 & 2 & -1 & 0 \\
 0 & 0 & 0 & 0 & -1 & 0 & -1 & 3 & -1 \\
 0 & 0 & 0 & 0 & 0 & -1 & 0 & -1 & 2
 \end{bmatrix}
 \begin{bmatrix}
 2 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
 0 & 3 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
 0 & 0 & 2 & 0 & 0 & 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 3 & 0 & 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 & 4 & 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 & 0 & 3 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 & 0 & 0 & 2 & 0 & 0 \\
 0 & 0 & 0 & 0 & 0 & 0 & 0 & 3 & 0 \\
 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 2
 \end{bmatrix}
 \begin{bmatrix}
 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\
 1 & 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 \\
 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\
 1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 & 0 \\
 0 & 1 & 0 & 1 & 0 & 1 & 0 & 1 & 0 \\
 0 & 0 & 1 & 0 & 1 & 0 & 0 & 0 & 1 \\
 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 \\
 0 & 0 & 0 & 0 & 1 & 0 & 1 & 0 & 1 \\
 0 & 0 & 0 & 0 & 0 & 1 & 0 & 1 & 0
 \end{bmatrix}$$

L
 $D = \text{diag}(1^T W)$
 A

This looks like the second derivative operator! (Discrete approximation to 2nd gradient) / C'est le noyau Laplacien, une approximation à la deuxième dérivée.

Laplacian Operator on Images

Data is back!

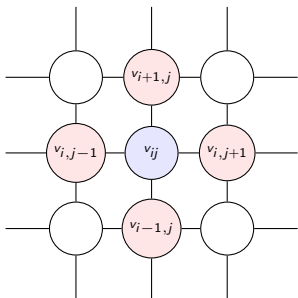


$$D = [1, -1] \quad L = \begin{bmatrix} 0 & -1 & 0 \\ -1 & 4 & 0 \\ 0 & -1 & 0 \end{bmatrix}$$

L is an edge detector here.

The Graph Laplacian Properties

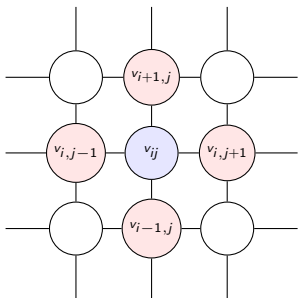
- We approximate the Laplace operator on the graph with Graph Laplacian / On approxime l'opérateur Laplace avec le Graph Laplacian.



- For undirected graphs L is symmetric. / Pour des graphs undirected L est symétrique.
- Off diagonals are non-positive. / Les non-diagonales sont non-positives.
- Rows add up to zero. / Les lignes s'ajoutent à zéro.

The Graph Laplacian Properties

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- Off diagonals are non-positive. / Les non-diagonales sont non-positives.
- Rows add up to zero. / Les lignes s'ajoutent à zéro.
- There's also the normalized Laplacian, $L_{\text{norm}} = D^{-1/2}(D - A)D^{-1/2}$, but we'll stick to L for now. / Il existe aussi la Laplacienne normalisé.

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The Graph Fourier Transform

- Given a Graph G containing a signal s , / Étant donné le graphe qui contient un signal s .
- Get Graph Laplacian L . / Obtiens la Laplacienne L .
- Do the eigenvalue decomposition on L . / Fait la décomposition éigen de L :

$$L = V\Lambda V^T$$

- Transform the graph signal / Transforme le signal dans le graphe,

$$S = V^T s$$

What does this mean?

- You can show that / On peut montrer que,

$$u^T L u = \frac{1}{2} \sum_{i,j=1}^N \underbrace{w_{ij}}_{Adj.} \underbrace{(u_i - u_j)^2}_{\text{local variation}}$$

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- What maximizes this measure of variation? / Que peut maximizer cette mesure de variation?
- $\max_u u^T L u$ s.t. $u^T u = 1$. What are these optimal u 's? / Que sont ces u 's optimales?

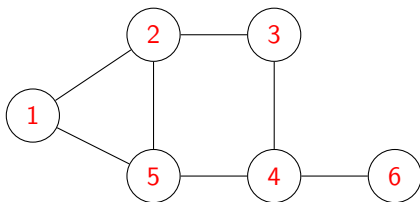
What does this mean?

- You can show that / On peut montrer que,

$$u^\top L u = \frac{1}{2} \sum_{i,j=1}^N \underbrace{w_{ij}}_{\text{Adj.}} \underbrace{(u_i - u_j)^2}_{\text{local variation}}$$

- What maximizes this measure of variation? / Que peut maximizer cette mesure de variation?
- $\max_u u^\top L u$ s.t. $u^\top u = 1$. What are these optimal u 's? / Que sont ces u 's optimales?
- Eigenvectors of u ! / Vecteurs propres de u !
- Also, note that larger $u^\top L^\top u$ is, higher frequency we have in the signal u . / Notez que plus $u^\top L^\top u$ est large, plus le signal dans u est de haute fréquence.

Example



$$\begin{bmatrix} 2 & -1 & 0 & 0 & -1 & 0 \\ -1 & 3 & -1 & 0 & -1 & 0 \\ 0 & -1 & 2 & -1 & 0 & 0 \\ 0 & 0 & -1 & 3 & -1 & -1 \\ -1 & -1 & 0 & -1 & 3 & 0 \\ 0 & 0 & 0 & -1 & 0 & 1 \end{bmatrix}$$

x	$x^T Lx$
$[1, 1, 1, 1, 1, 1]$	0
$[0, 0, 1, 1, 0, 0]$	3
$[1, 0, 1, 0, 1, 0]$	5

Low and High Frequency Graph Signals

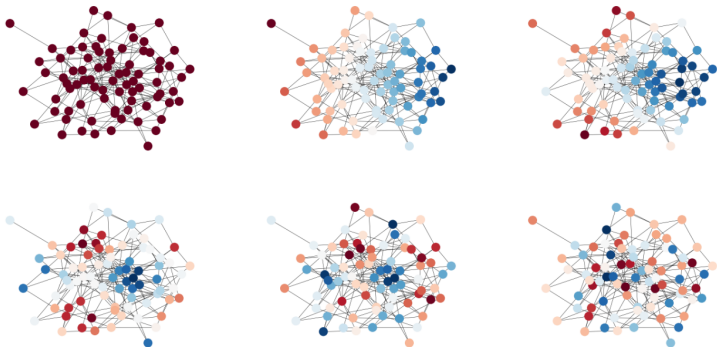
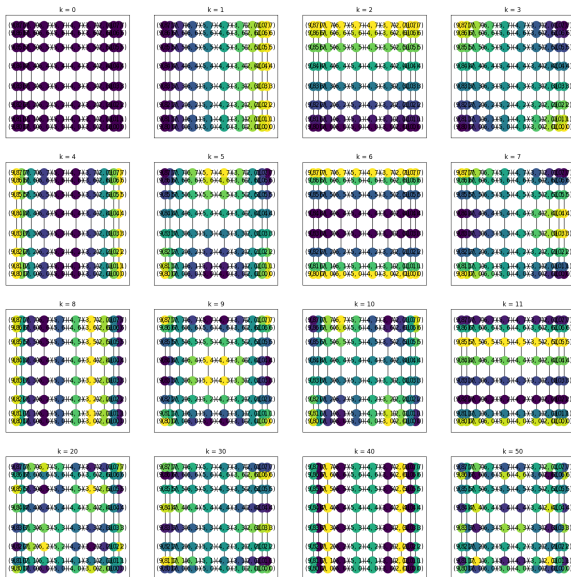
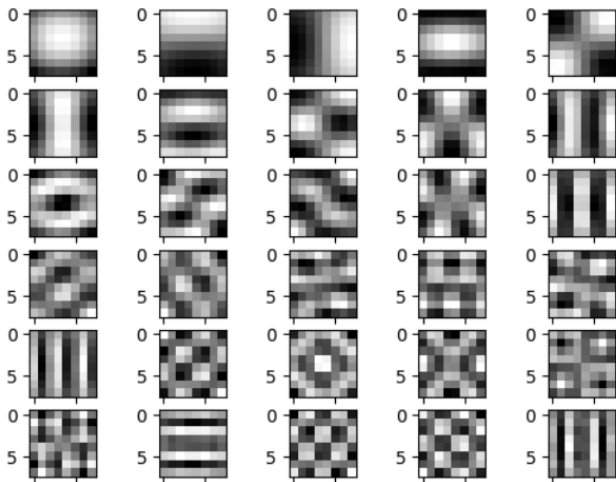


Image taken from UIUC MLSP class

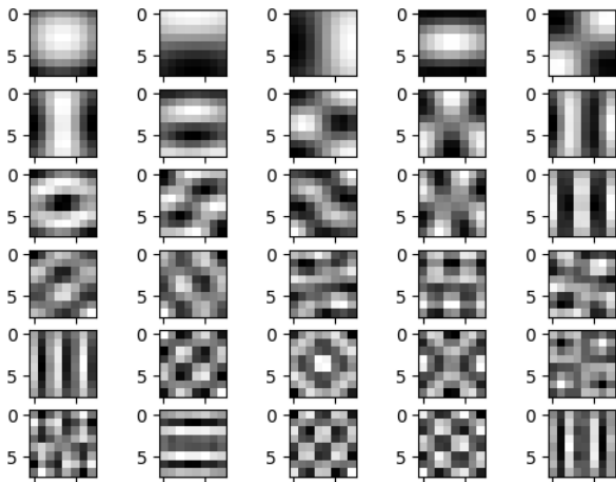
Grid Graph



Do you remember this?



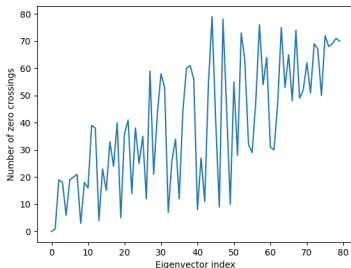
Do you remember this?



- It seems we were learning eigenvectors that correspond to a grid graph!
 - ▶ On apprendait des vecteurs propres qui correspondent à un graphe grille!

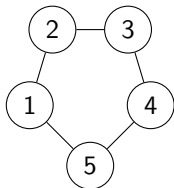
Eigenvalues as a measure of frequency

- The eigenvalues measure graph frequency
 - ▶ Les valeurs propres mesurent la fréquence de chaque base
- We can rank the eigenvectors by their eigenvalues / On peut mettre les vecteurs propres par leur valeurs propres
 - ▶ First eigenvectors are slow / change slowly. Les premiers vecteurs propres changent lentement
- The number of zero crossings for each eigenvector / le nombre de croisements zeros pour chaque vecteur propre:



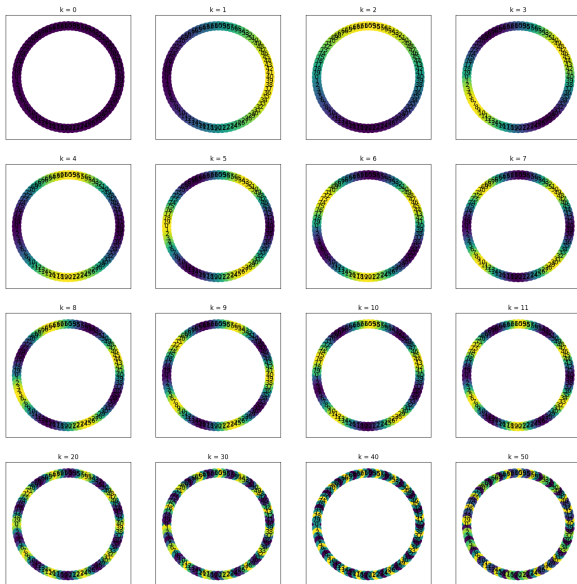
Special Case: DFT

■ Undirected Ring Graph



$$A = \begin{matrix} & \text{to} & & & \\ \begin{matrix} 0 & 1 & 0 & 0 & 1 \\ 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 1 \\ 1 & 0 & 0 & 1 & 0 \end{matrix} & & \text{from} & & \end{matrix}$$

- Eigenvectors of L correspond to the Discrete Fourier Transform (DFT)! / Les vecteurs propres de L correspondent à DFT!



- Paired Sine / Cosine Bases,

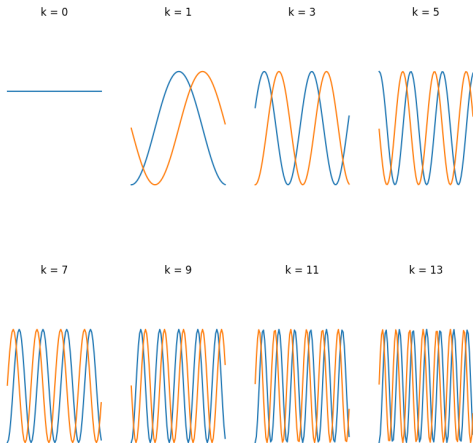
$$u_k(n) = \exp(j2\pi kn/N)$$

.

DFT Bases

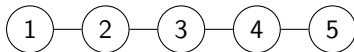
■ Paired Sine / Cosine Bases,

$$u_k(n) = \exp(j2\pi kn/N) = \cos(2\pi kn/N) + j \sin(2\pi kn/N)$$



Special Case 2, Discrete Cosine Transform

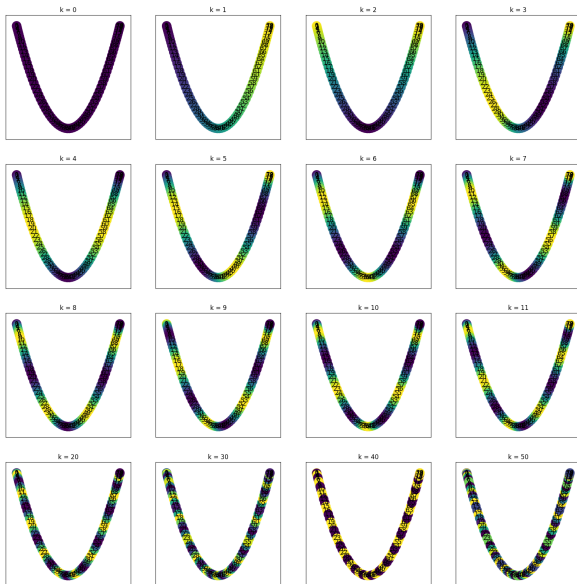
■ Undirected Path Graph



$$A = \begin{matrix} & \begin{matrix} \text{to} \\ \hline \end{matrix} & \begin{matrix} 0 & 1 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 & 0 \end{matrix} \\ \begin{matrix} \hline \\ \text{from} \end{matrix} & & \end{matrix}$$

■ Eigenvectors of the Graph Laplacian will correspond to the DCT bases!

- ▶ Les vecteurs propres du Laplacien correspondent aux bases DCT!



DCT-Type2 Bases

- Paired Sine / Cosine Bases,

$$u_{m,k}(n) \propto \cos((m + 0.5)k\pi/N)$$

.

DCT-Type2 Bases

■ Paired Sine / Cosine Bases,

$$u_{m,k}(n) \propto \cos((m + 0.5)k\pi/N)$$

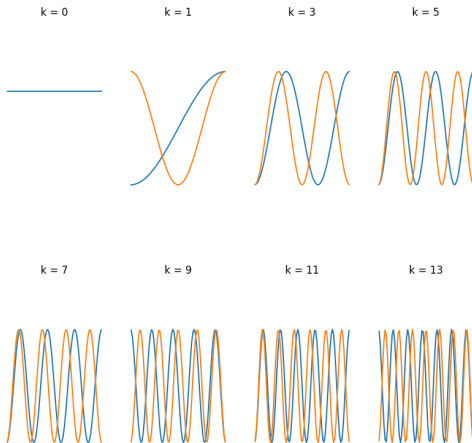


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Imposing a Graph

- Recap so far / Sommaire de ce qu'on a vu:
 - ▶ Graphs are collection of nodes and edges. / Un graphe est une collection des nodes et des edges.
 - ▶ A node is defined by an adjacency matrix A / Un graphe est défini par un adjacency matrix A .
 - ▶ Graph Laplacian $L = D - A$.
 - ▶ Is used to compute the Graph Fourier Transform. / Est utilisé pour calculer le Graph Fourier Transform.
 - ▶ This generalizes the classical Fourier Transform / Ça généralise le Fourier Transforme.
- We understand that standard SP assumes an underlying graph / Tout ça nous montre que le SP classique suppose un graphe.
 - ▶ Can we adjust the graph so that it's more suitable? / Peut-on ajuster le graph pour qu'il est plus ajusté?

Defining a Graph from a Signal

- We can define adjacency based on spatial location / On peut définir le voisinage en utilisant le localisation spatiale, temporelle

$$A_{ij}^t = \exp(-\alpha \|t_i - t_j\|)$$

- Or, we can define an adjacency based on sample values / Ou, on peut définir le voisinage en utilisant les valeurs
 - ▶ Do you remember this from somewhere else? / Souvenez-vous de ça d'ailleurs?

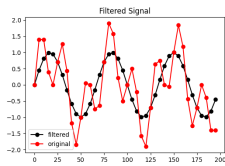
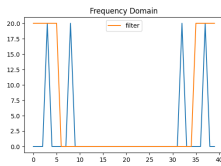
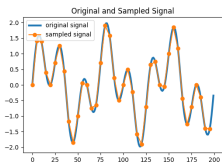
$$A_{ij}^x = \exp(-\beta \|x_i - x_j\|)$$

- We can define an overall adjacency matrix / On peut définir un matrice de voisinage ultime:

$$A = \gamma A^t + (1 - \gamma) A^x$$

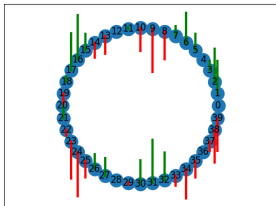
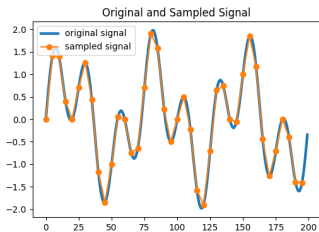
Classical filtering

■ $x_t = \cos(3\omega t) + \cos(8\omega t)$

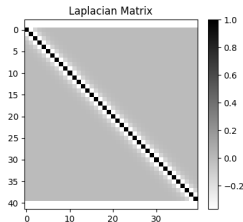
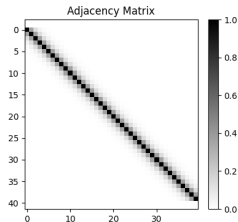


Let's do the same thing with Graphs

- Now we will define the same signal on a graph / On définit maintenant le meme signal sur un graphe

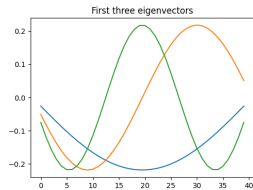
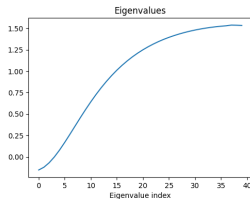
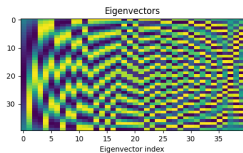


- Adjacency matrix, and the Laplacian (for a cycle graph)
 - $A_{ij} = \exp(-\alpha \|t_i - t_j\|)$



Step 1: Obtain the frequency bases of L

■ $L = V\Lambda V^T$



Graph Filtering Steps

- Transform onto the graph Laplacian eigenvectors.

$$X = \underbrace{V^T}_{\text{Eigenvec.}} \underbrace{x}_{\text{signal}}$$

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$$\hat{x} = VZ$$

Graph Filtering Steps

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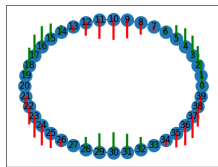
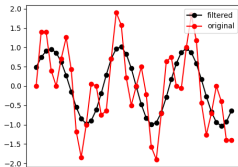
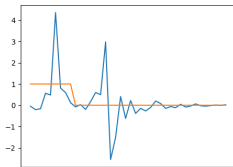
$$X = \underbrace{V^T}_{\text{Eigenvec.}} \underbrace{x}_{\text{signal}}$$

- Multiply with filter F

$$Z = F \odot X$$

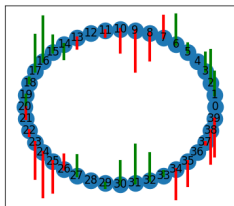
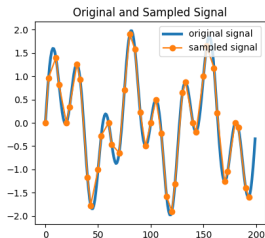
- Reconstruct

$$\hat{x} = VZ$$

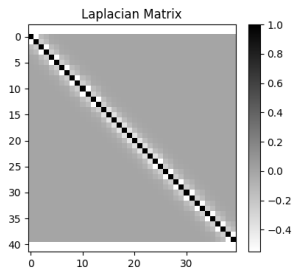
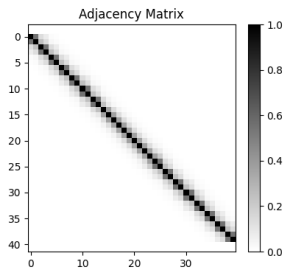


Nothing new with this, so why?

- What if the sample rate was not as regular / Et si le taux d'échantillonnage n'était pas si régulier?
- We can use a corresponding irregular graph maybe? / On peut utiliser la graph qui correspond?

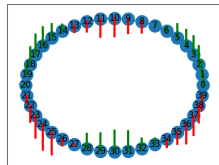
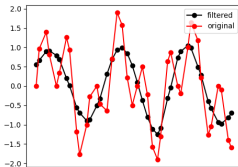
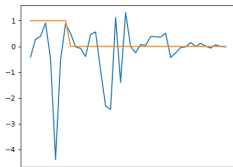


The new graph structure



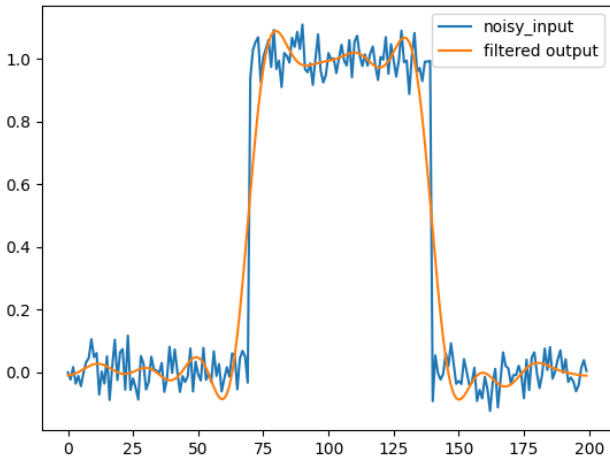
Non Uniform Graph Filtering

- We can still apply the same process as before / On peut encore appliquer le meme processus



Encoding context from a signal

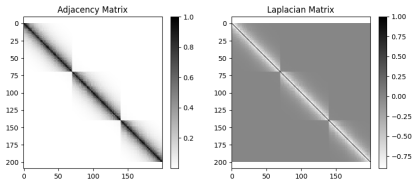
- Consider this noisy signal with steep edges / Considerons ce signal avec des sautes



Using the signal in the adjacency

- Can we somehow encode that closer values are similar? / Peut-on encoder que les valeurs qui sont proches sont plus similaires?
- Adjacency matrix:

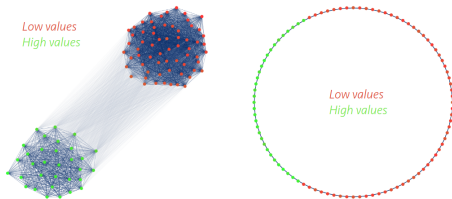
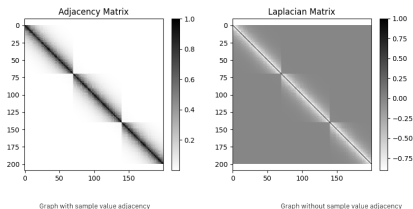
$$A_{ij} = \exp(-\alpha \|t_i - t_j\| - \beta \|x_i - x_j\|)$$



Using the signal in the adjacency

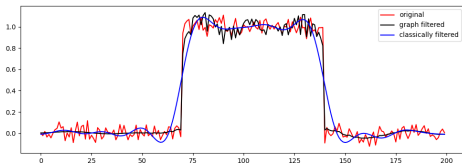
- Can we somehow encode that closer values are similar? / Peut-on encoder que les valeurs qui sont proches sont plus similaires?
- Adjacency matrix:

$$A_{ij} = \exp(-\alpha \|t_i - t_j\| - \beta \|x_i - x_j\|)$$



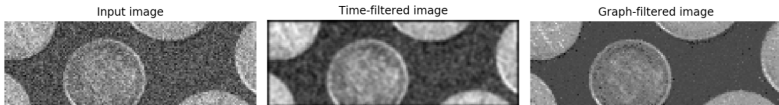
Edge preserving filter

- We can see that the graph filtering better preserves the edges / On voit que le filtre de graph mieux protège les sautes.



Edge preserving 2D example

- We can also apply the same thing on 2D signals / On peut appliquer la meme affaire sur des signaux 2D aussi.



Defining Graphs from Data

- We already did this! / On a déjà fait ça
 - ▶ Eigendecomposition on an affinity matrix = KPCA/MDS/ISOMAP.
 - ▶ Clustering the eigenvectors = Spectral Clustering.

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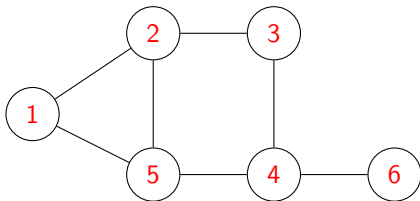
Graph Signal Processing in Action

Graph Convolution

Graph Neural Networks

Filtering in the graph spatial domain

- In regular signals we have the frequency domain / time domain filtering duality. / Dans les signaux réguliers on a une dualité entre filtrage dans le domaine de temps / domaine de fréquence.
- Filtering in the time domain is defined by convolution which uses shifts. Filtrage dans le domaine de temps utilise des shifts.
- We can also define a shift operator on graphs. / On define a shift operator over graphs



$$S = \begin{bmatrix} 1 & 1 & 0 & 0 & 1 & 0 \\ 1 & 1 & 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 & 0 & 1 \end{bmatrix} = I + A$$

Graph Filtering / Convolution

- Graph filtering definition: $h * x = \sum_k h_k S^k x$
- For instance for $h = [1, 1, 0.5]^\top$, $x = [-1, 2, 0, 0, 0, 0]^\top$

$$S = \begin{bmatrix} 1 & 1 & 0 & 0 & 1 & 0 \\ 1 & 1 & 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 & 0 & 1 \end{bmatrix} = I + A$$

$$Sx = [1, 1, 2, 0, 1, 0]^\top, \quad S^2x = [3, 5, 3, 3, 3, 0]^\top$$

$$y = h_0x + h_1Sx + h_2S^2x = [1, 5, 2.5, 1.5, 2, 0]^\top$$

Graph Filtering / Convolution

- Graph filtering definition: $h * x = \sum_k h_k S^k x$
- For instance for $h = [1, 1, 0.5]^\top$, $x = [-1, 2, 0, 0, 0, 0]^\top$

$$S = \begin{bmatrix} 1 & 1 & 0 & 0 & 1 & 0 \\ 1 & 1 & 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 & 0 & 1 \end{bmatrix} = I + A$$

$$Sx = [1, 1, 2, 0, 1, 0]^\top, \quad S^2x = [3, 5, 3, 3, 3, 0]^\top$$

$$y = h_0x + h_1Sx + h_2S^2x = [1, 5, 2.5, 1.5, 2, 0]^\top$$

- Notice that S defines a kernel with which we convolve! / Notez que S implique une sorte de noyau de convolution!

To summarize

- Signals can be defined as graphs / Signaux peut-être défini comme des graphes.
 - ▶ It enables us to represent more structured sample relations / Ça nous permet d'établir des relations plus structurées entre les échantillons.
- We can define analogs to classical DSP / On peut définir des analogues aux DSP.
- Now, let's briefly mention that we can do ML also! / On peut faire du ML aussi!

Table of Contents

Graph Basics

Example Graphs

Graph Signal Processing

The Graph Laplacian

Graph Fourier Transform

Graph Signal Processing in Action

Graph Convolution

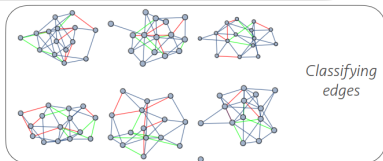
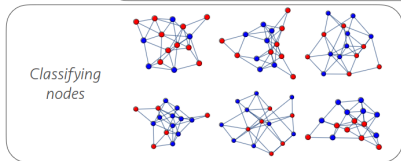
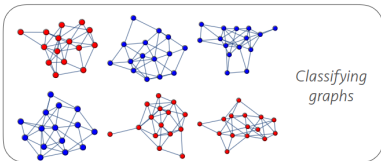
Graph Neural Networks

Graph Neural Networks

- Neural Nets that operate on graphs. / Neural Nets qui fonctionnent sur des graphes.
 - ▶ Using the graph shift matrix, we can define CNNs, RNNs.. / On peut définir des CNNs / RNNs en utilisant l'opérateur graph shift.
- Useful for things like / Utile pour des choses comme:
 - ▶ Molécules, social graphs, mesh representations, LIDAR, ...
- Hot topic / Je ne suis pas expert du tout!

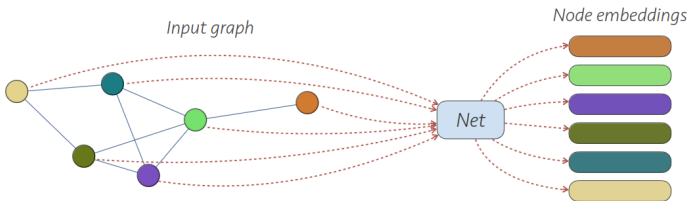
Types of Graph Level Processing

- Graph Level Processing, e.g. classifying a molecule
- Node Level Processing, e.g. LIDAR pixel classification
- Edge Level Processing e.g. Relationship classification in a social network



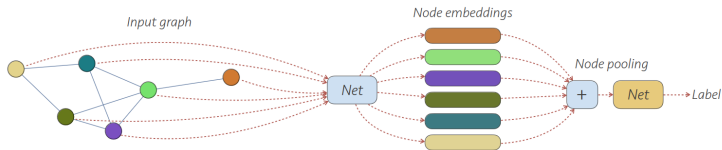
A very naive Graph Neural Network

- We can embed the nodes only / On embed les nodes seulement
 - ▶ Like you can do on your spectra in HW2-Q2 :)



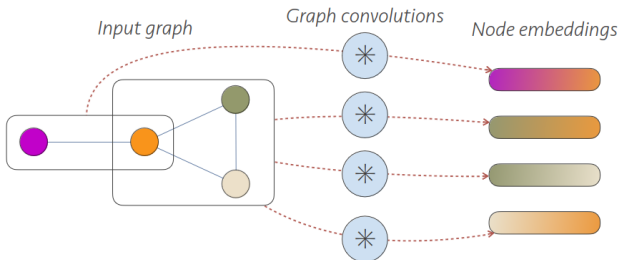
A very naive Graph Neural Network

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Adding the graph structure

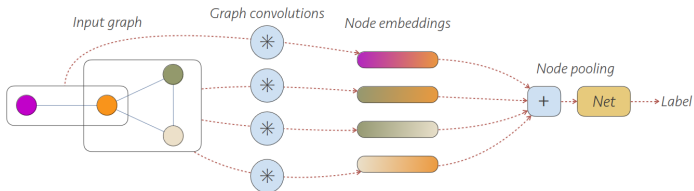
- We can also use graph convolutions to combine neighboring nodes when computing the node embeddings / On peut aussi inclure des convolutions graphes quand on calcule les node embeddings.
 - ▶ This enables us to model the graph structure / Ça nous permet de modéliser la structure de la graphe.



- Instead of using CNNs, it's possible to use RNNs / Attention Models, all that / Au lieu d'utiliser des CNNs, c'est possible d'utiliser des RNNs, modèles d'attention.

Adding the graph structure

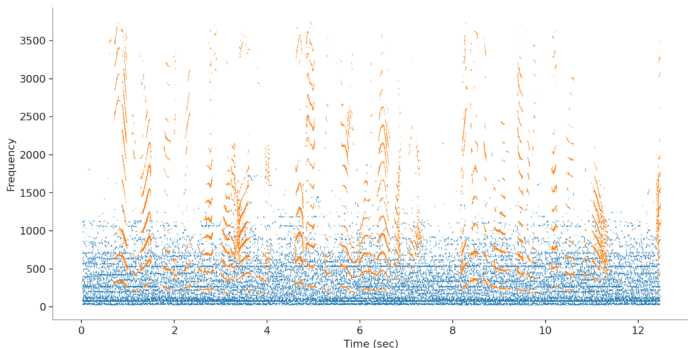
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Audio Example

- Using point clouds for a spectrogram / Nuage de points pour un spectrogram (Look up re-assigned spectrograms)



- Instead of having series of vectors, we have a point cloud / on a un nuage de points au lieu de vecteurs: $C = [(f_1, t_1), (f_2, t_2), \dots, (f_N, t_N)]$.
- The paper (see the reading list) claims that training is faster, model is smaller, performance is better. (Best paper award in WASPAA 2021). / Le papier dit que l'entraînement est plus rapide, modèle est plus petit, et la performance est mieux.

Recap

- Signals are graphs! It's better to be aware of that to be able to generalize. / Les signaux sont des graphs en tout cas! Si on voit ça, on peut generaliser.
- Signal processing with Graph Perspective / Traitement du Signal avec un Perspective de Graphe
 - ▶ The Graph Fourier Transform
- Graph Neural Networks
 - ▶ Useful in many structured data domains (e.g. drug design) / Utile dans plusieurs données avec structure

Reading Material

- Graph Signal Processing:
<https://arxiv.org/pdf/1712.00468.pdf>
- GNN tutorial:
<https://distill.pub/2021/understanding-gnns/>
- Audio point cloud GNN stuff:
<https://arxiv.org/pdf/2105.02469.pdf>

Next and last week

- I will talk about speech/audio. But let me know if you want me look into other things also. / Je vais parler sur speech/audio. Mais laissez-moi savoir si vous voulez voir d'autres sujets aussi.